

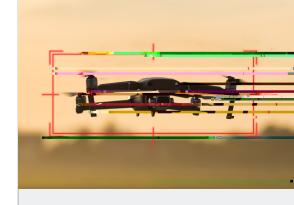
UAS TRACER

Unmanned Aerial System (UAS) Threat Recognition and Counter Enabler (TRACER)

UAS TRACER is designed to perform object detection of a UAS using raw inputs from single or multiple distributed EO/IR sensors. The included track aggregation capability fuses target data from additional, distributed tracking systems from various sources, including but not limited to, EO/IR, radar, RF, and acoustic systems.

The combined de ec and rack capabili ie ha e been de eloped in order o pro ide i a ional a arene , arge acq i i ion, recogni ion, and ranging of a ide arie of UAS. The en or-agno ic rack aggrega ing em deli er UAS arge a e e ima ion (TSE) o o her er in an o erall CUAS ol ion.

UAS TRACER i capable of in erfacing i ho her TSE er, cha Sore Managemen S em (SMS) o enable UAS engagemen . I pro ide an op ional remo e GUI for opera or con rol and da a di pla. When connec ed o an L3Harri MX-Serie



Software-defined, modular, open architecture track aggregating CUAS capability that includes:

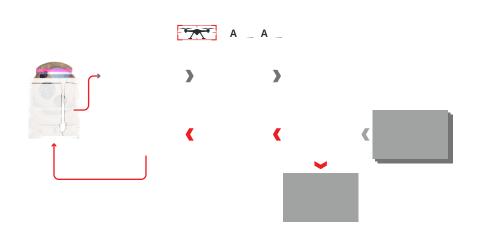
- > An EO/IR compute capability for image processing, detection and tracking of UAS
- > Track aggregation to ingest target tracks from various sources, e.g., radar, RF and acoustic sensors, resulting in TSE
- > Pointing and Command & Control



- > Edge Detection
- > Motion Detection
- > AI/ML Detection
- > Pixel Intensity Detection

TYPES OF TRACKERS AND **AGGREGATION**

- > Relative Motion Tracking
- > Unscented Kalman Filtering
- > Fusion Tracking
- > Rate Deflect Tracking



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Non-E por Con rolled Informa ion. The eiem()/da a ha ebeen re ie ed in accordance i h he In erna ional Traf c in Arm Reg la ion (ITAR), 22 CFR par 120.34 and he E por Admini ra ion Reg la ion (EAR), 15 CFR 734(3)(b)(3), and ma be relea ed i ho e por re ric ion

L3Harri Technologie i he Tr ed Dirporin he defen e ind r. Wihc omer'mi ion-criical need al a in mind, o r 50,000 emplo ee deli erend- o-end echnolog ol ion connec ing he pace, air, land, ea and c berdomain in he in ere